

Flying the Garmin G1000

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SMX-XX April 2008



Primary Flight Display (PFD)

Multi-Function Display (MFD)

An intro to glass panels...

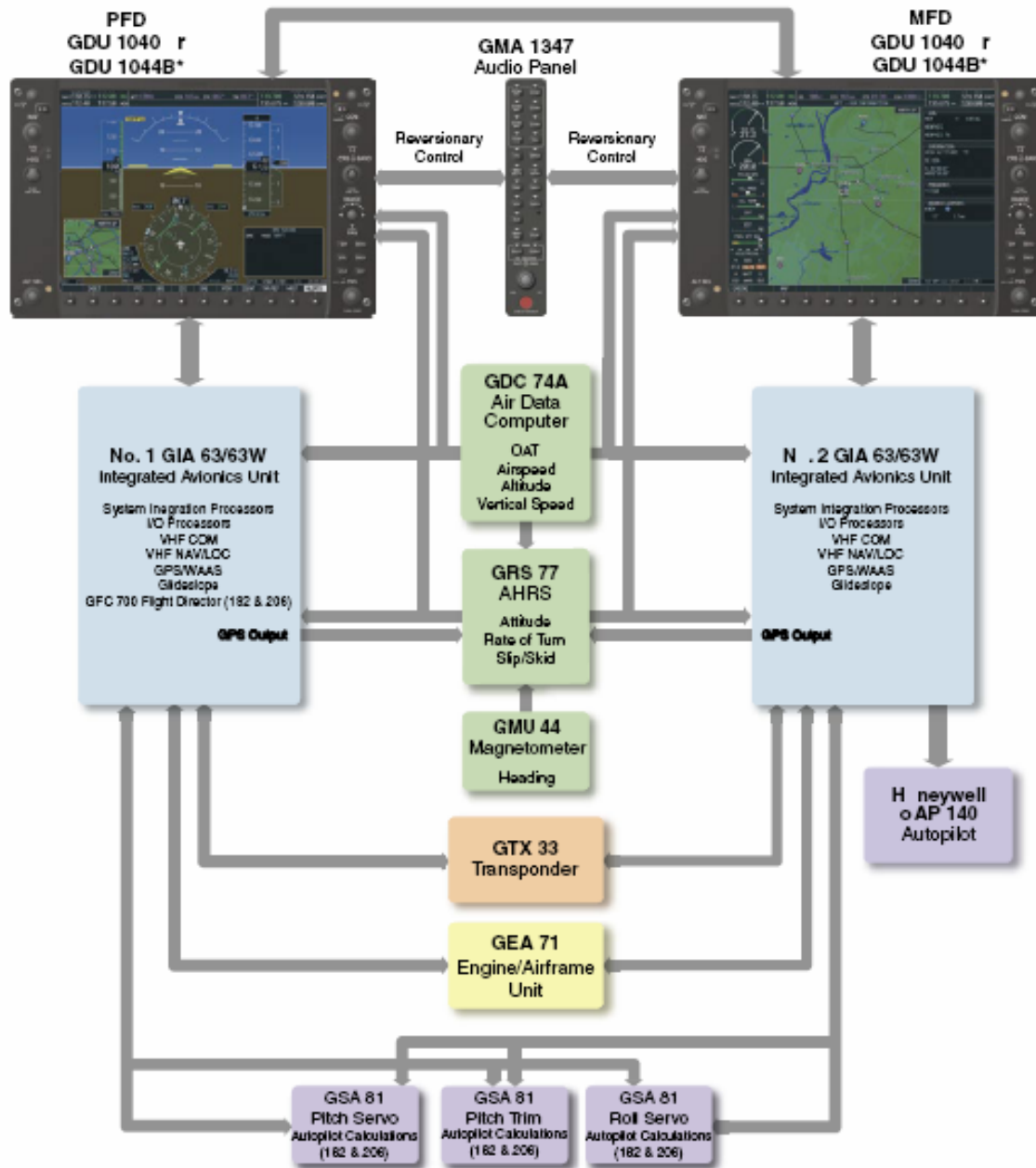
Garmin's G1000 panel dominates the *new* airplane market



Cessna 172, 182, T206
Beech G36
Columbia 400
Diamond DA40, DA42
Mooney Ovation 20R
Tiger AG-5B
VLJ's etc...

- The promise is greater functionality at lower cost.
- Better maintainability and reliability than analog instrumentation?
- Not just data, but information.

It's modular...



The G1000 is a integrated system of communicating modules.

Service is primarily swapping LRUs and repairing them in-house or back at Garmin.

The various LRUs are common to many different airframes from the C172 to VLJs.

I'm familiar with the C172S configuration, so I'll concentrate on that.

In the G1000 flight data are measured by remote sensors and displayed on the PFD.

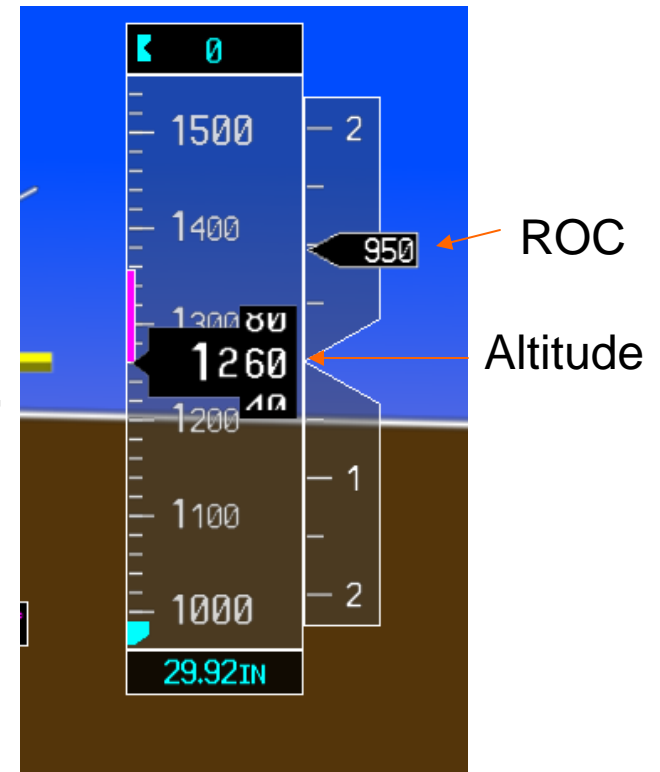


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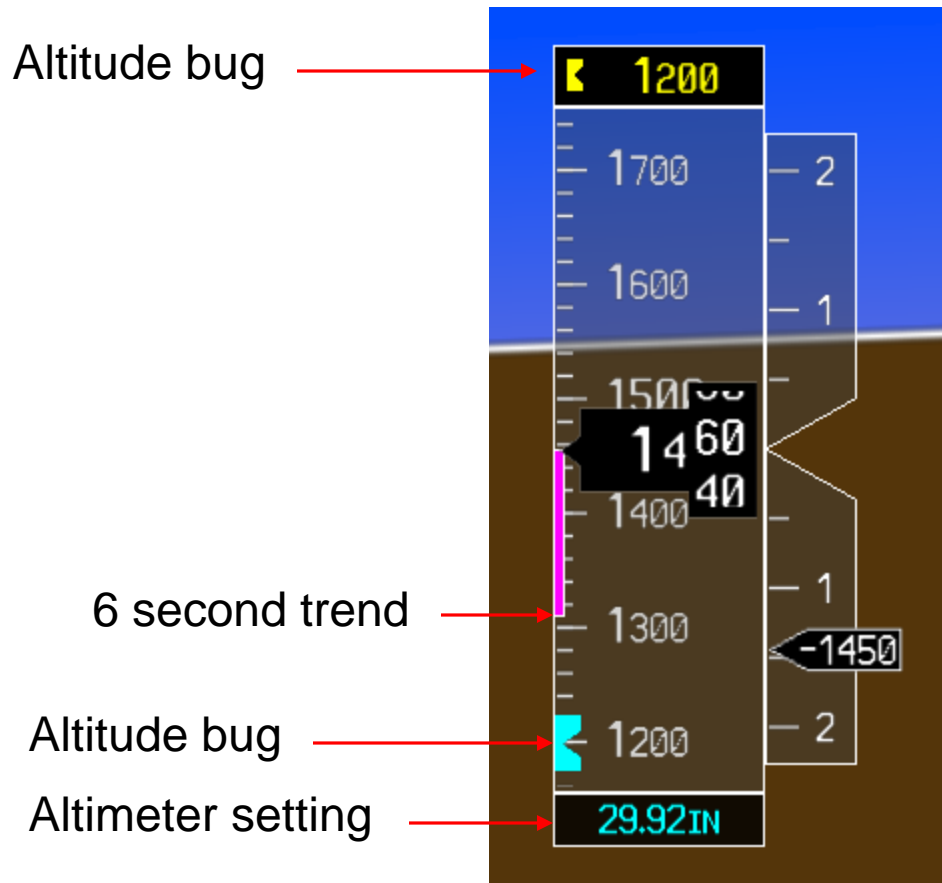
GDC74A air data computer

+



Solid state electronic pressure sensors replace mechanical instruments.
Sensor and display are separate.

In addition we have an altitude bug and a 6-second trend vector.



The altitude bug is not integrated with the KAP140 autopilot. It has to be set independently.

In the C172S/G1000/KAP140, there are three altimeters to set!

Garmin has recently introduced its own integrated autopilot.

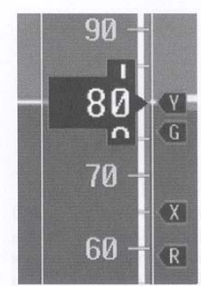
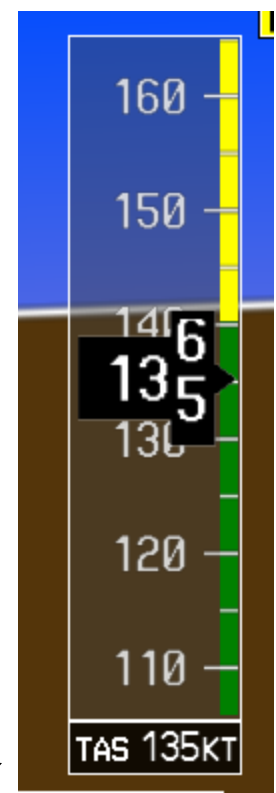


Garmin
GFC700
A/P

The altimeter is set with the outer knob of the OBS course selector on the RH bezel.



The airspeed indicator is also replaced with a tape.



TAS is computed automatically.
Vr, Vx, Vy bugs can be adjusted from the defaults.

REFERENCES			
TIMER	00:00:00	UP	START?
GLIDE	76KT		◀ ON ▶
Vr	59KT		◀ ON ▶
Vx	65KT		◀ ON ▶
Vy	80KT		◀ ON ▶

XPDR	1200	ALT	R	LCL	15:30:30
IDENT	TMR/REF	NRST	ALERTS		

Attitude and heading data comes from the AHRS



GRS77 attitude and heading reference system



3-axis magnetometer

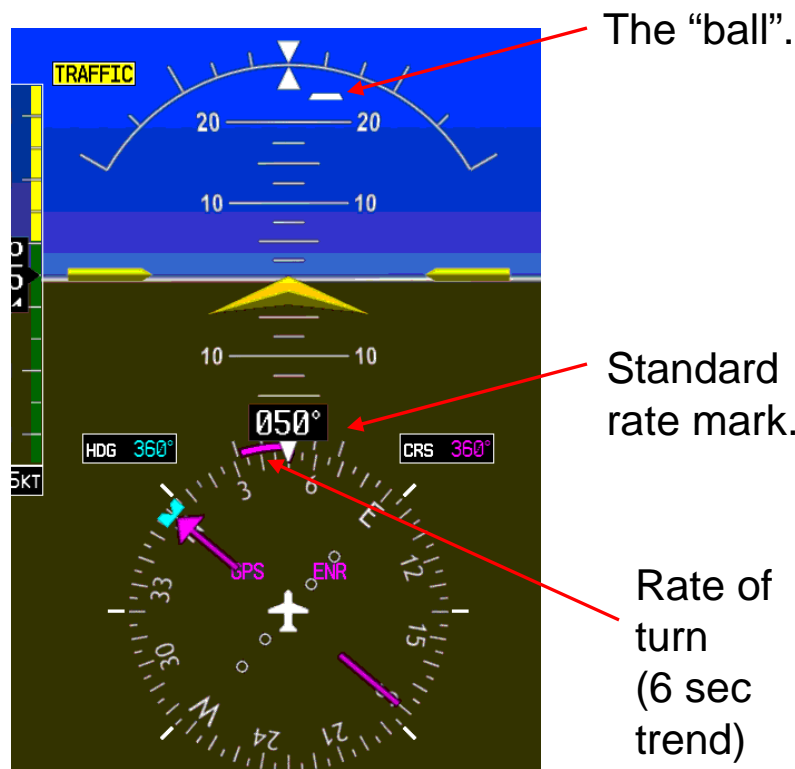
AHRS has MEMS accelerometers rate-of-turn and tilt sensors in all three axes to provide an inertial reference system (IRS).

Magnetometer, GPS and air data input are used for initial initialization and to assist in attitude determination.

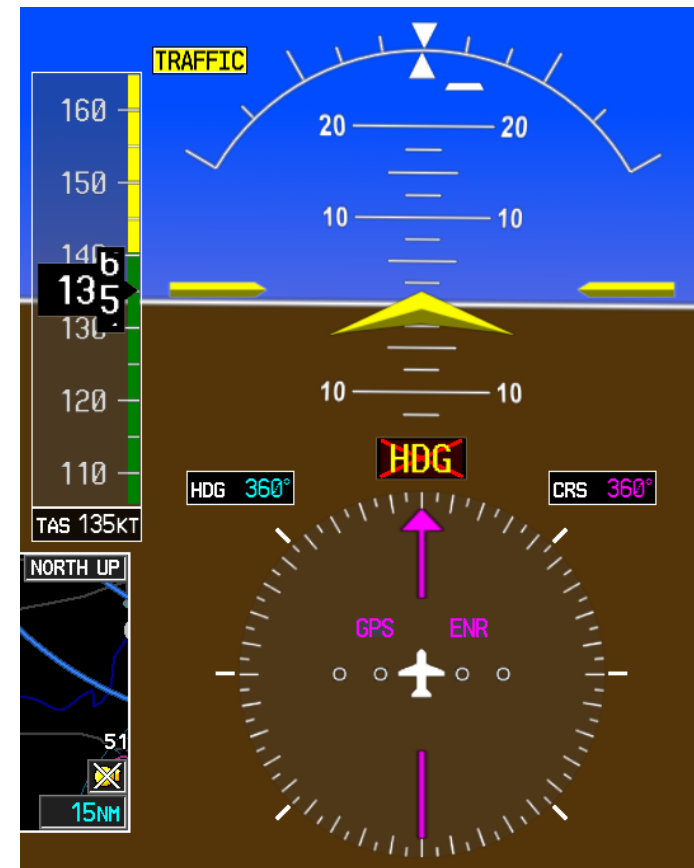
Unlike a traditional gyro-based IRS, the AHRS can re-erect while in motion and even in flight. (Even in a 20 degree bank!)

The AHRS will degrade into a reversionary mode if external inputs are lost. It has some redundancy...

AHRS Mode	Available AHRS Functions			Available Sensor Inputs		
	Pitch	Roll	Heading	GPS Input (At least one)	GMU 44 Magnetometer	GDC 74A Air Data Computer
Normal/Primary	X	X	X	X	X	X
Reversionary: No GPS	X	X	X	-	X	X
Reversionary: No Magnetometer	X	X	-	X	-	X
Reversionary: No Magnetometer No Air Data	X	X	-	X	-	-



Normal AHRS



AHRS w/o magnetometer

The heading display incorporates an HSI for the primary navaid (GPS, VOR or ILS).

NAV1 117.95 ↔ 111.40 RIS
NAV2 108.00 117.95

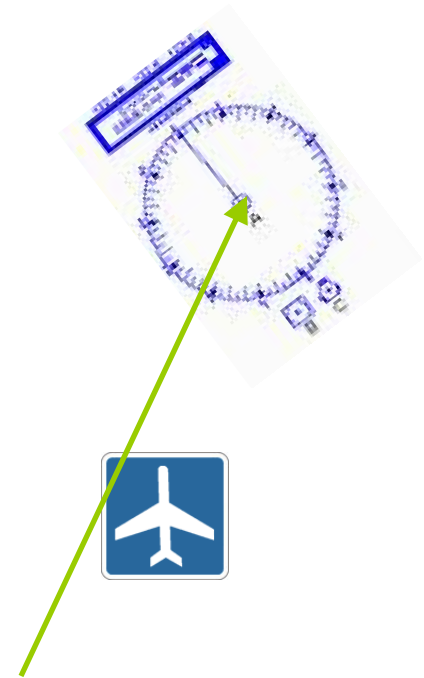
NAV1 active is 111.4 (RIS)
Standby is 117.95.



Primary nav on the HSI
toggled with the CDI
soft-key

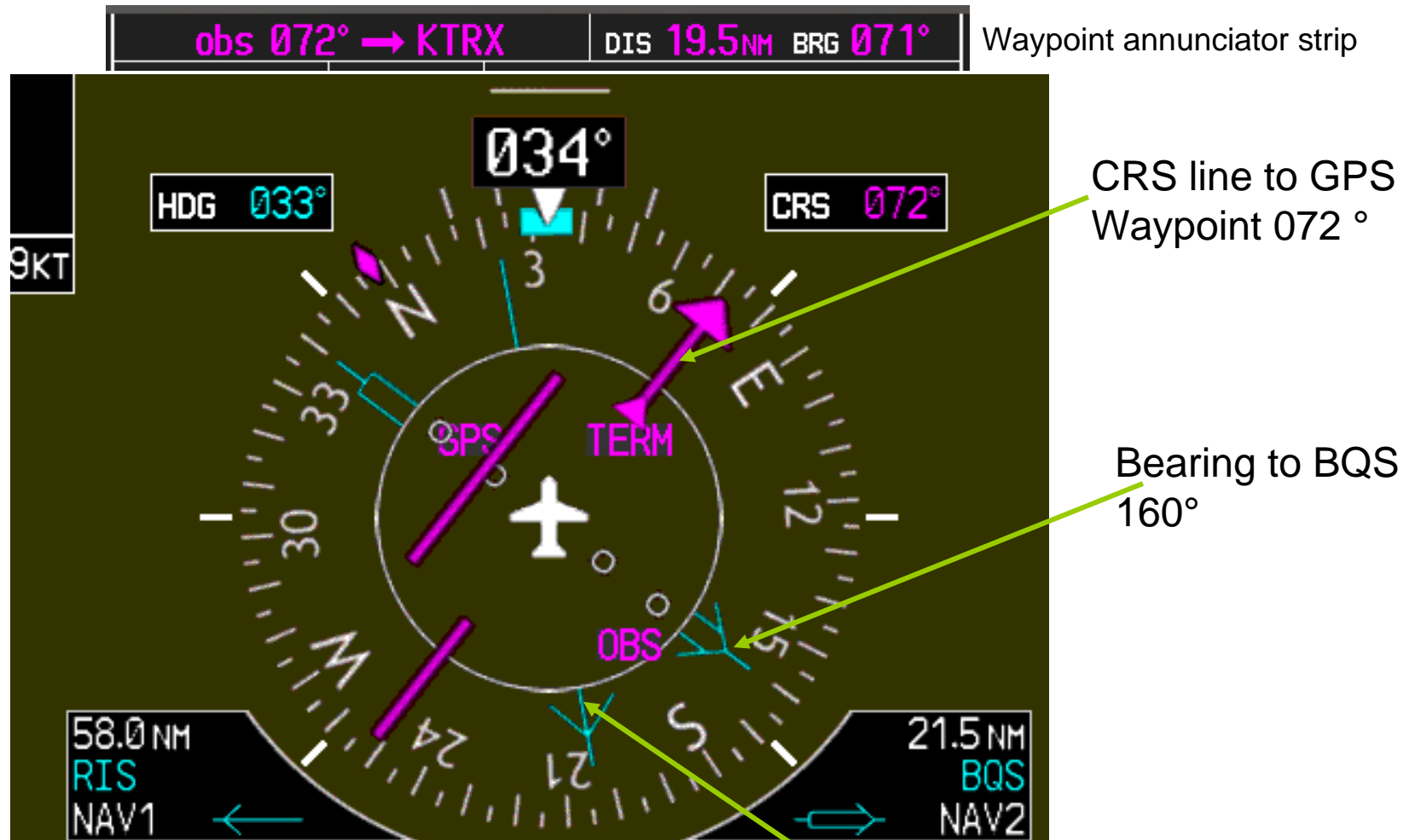


Inner knob sets
the "OBS" course
pointer. Pressing
gives "direct-to".



We are intercepting the
071° bearing to RIS VOR
on a 042° heading.

To simultaneously display *secondary* nav info you can display RMI pointers



Our primary nav, on the HSI, is the 072° GPS course to KTRX. RMI pointers show bearings to NAV1&2 VORs.

Bearing to RIS 203°

Here we show the whole Primary Flight Display...



It's all electrical except for three standby instruments



Airspeed, Attitude & Altimeter

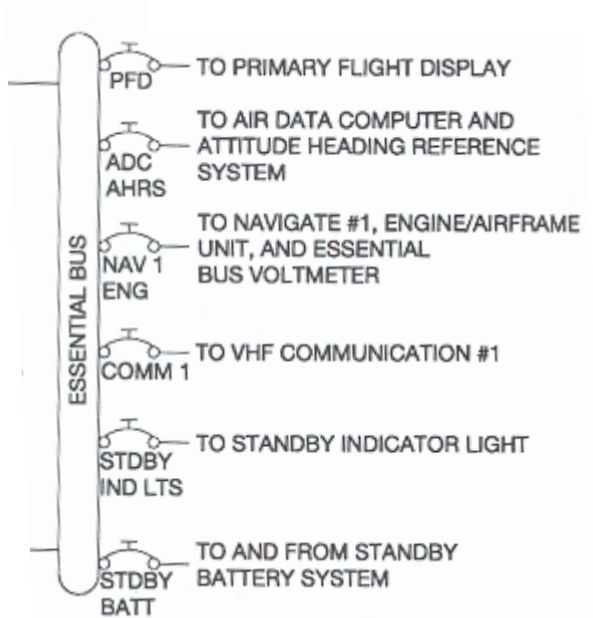
If a panel fails, the remaining panel can operate in *reversionary* mode.
(Automatic or the red button.)

In reversionary mode, the PFD display adds engine instrumentation.



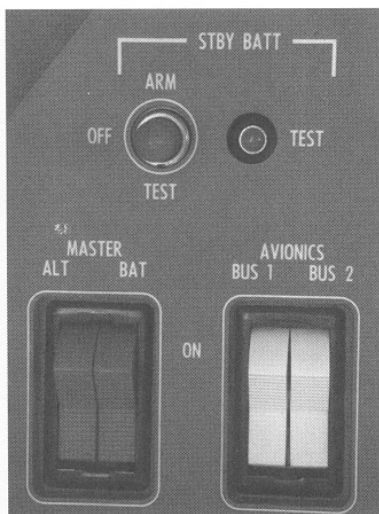
Normally, engine data only shows on the MFD.

In the C172/Garmin 1000 a standby battery can power the essential bus.



- *Essential* bus powers PFD, AHRS, engine/airframe sensors, #1 Nav-Com and 1 GPS.
- If the alternator fails, turning off the master switch and leaving the stand-by battery switch *armed* will allow you to preserve main battery capacity for later in the flight.
- The standby battery has little or no power remaining once the essential bus voltage drops to 20V.

(excerpted from the C172S manual)

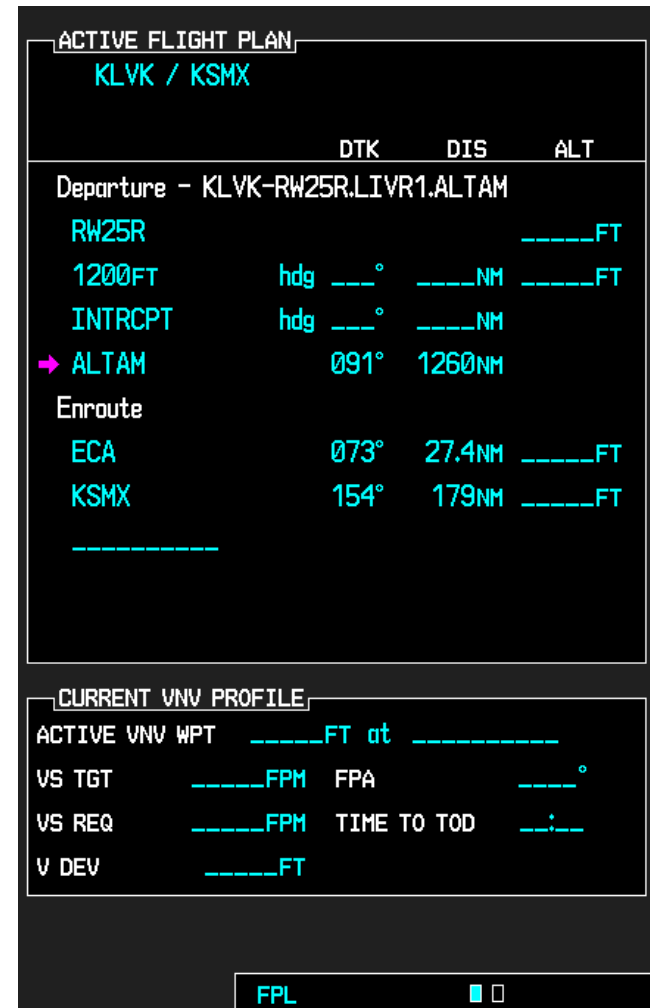


From the starting checklist:

4. STBY BATT Switch – TEST (hold for 20 sec, verify the green test lamp does not go out), then ARM (verify PFD comes on)

checks the condition of the standby battery.

The GPS interface will be familiar to Garmin 430/530 users.



FPL on the PFD

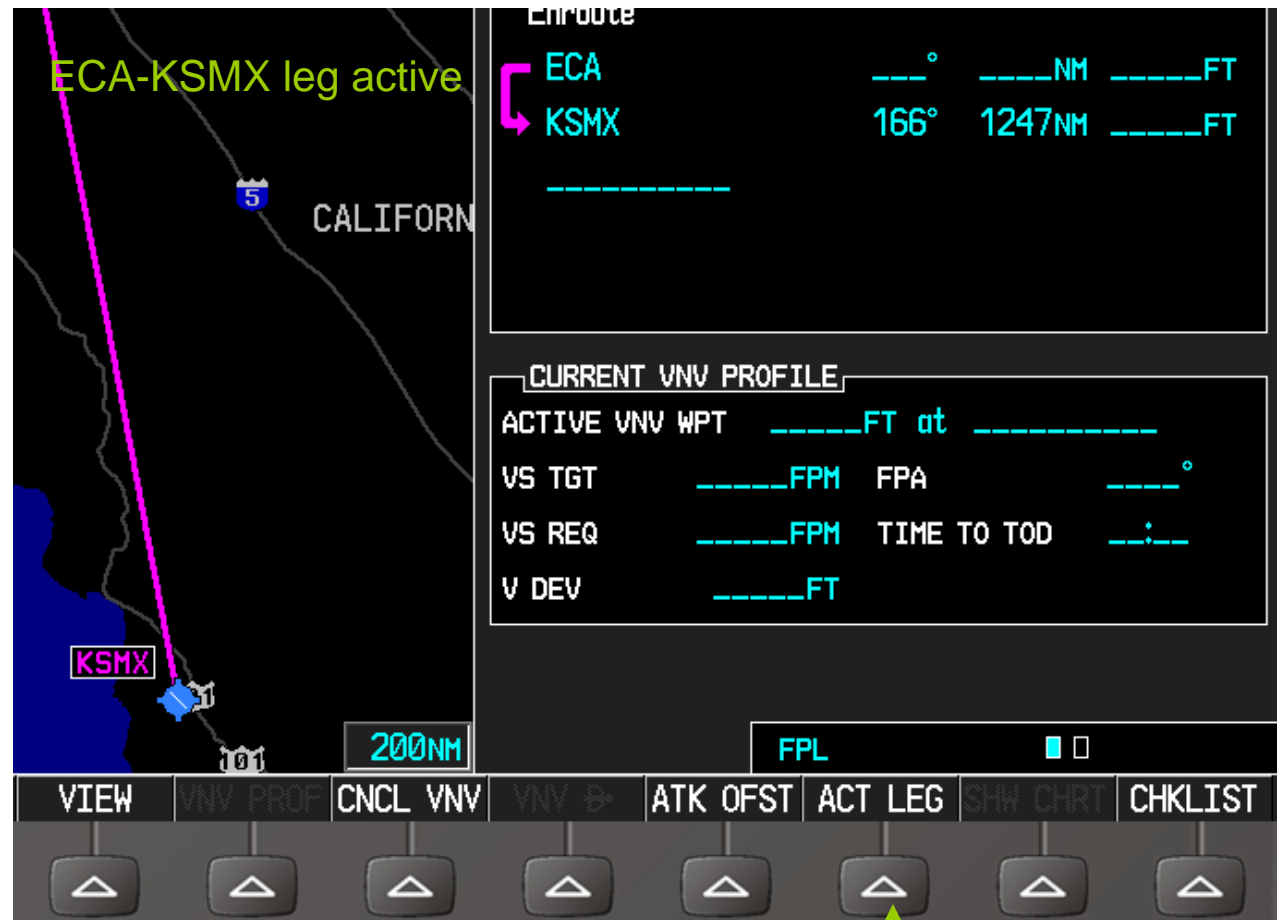


More extensive planning options on the MFD page.

Curiously, the direct/direct shortcut for activating a flight plan leg is absent on the G1000.

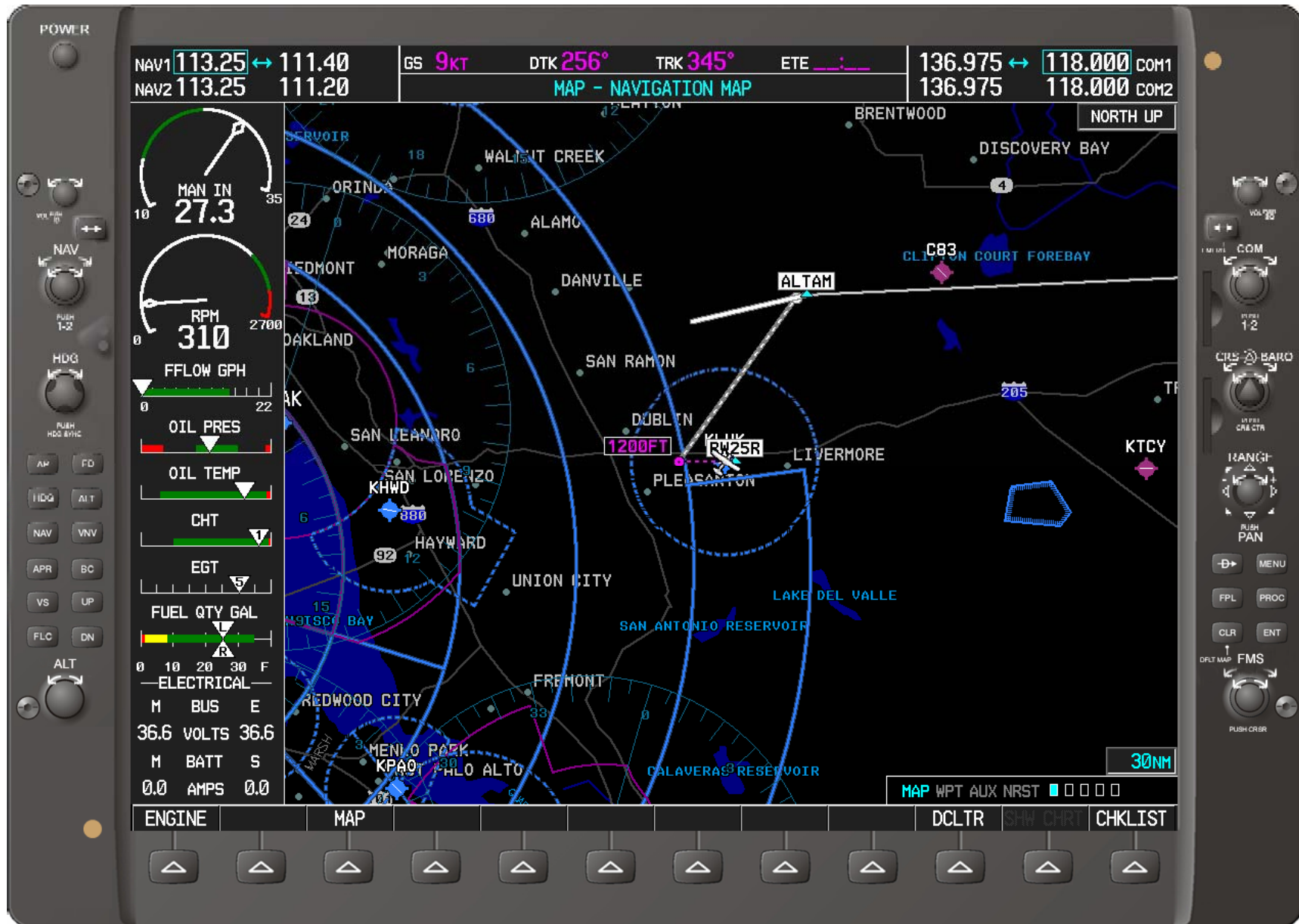


You can still use *activate leg* via the *menu* key, or on the MFD only, use the *act-leg* soft-key.

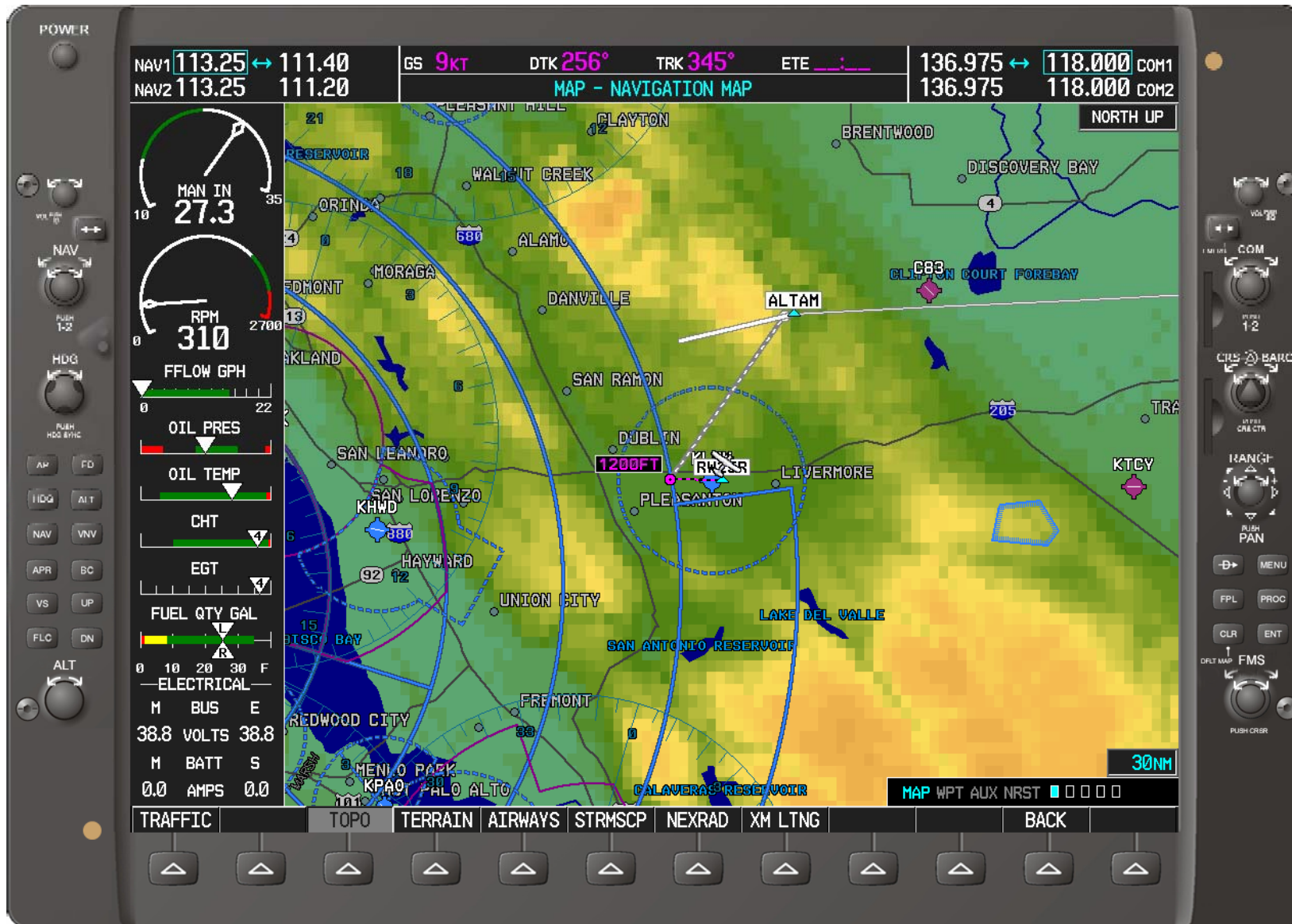


Soft key.

The MAP page on the MFD shows the flight plan and position.

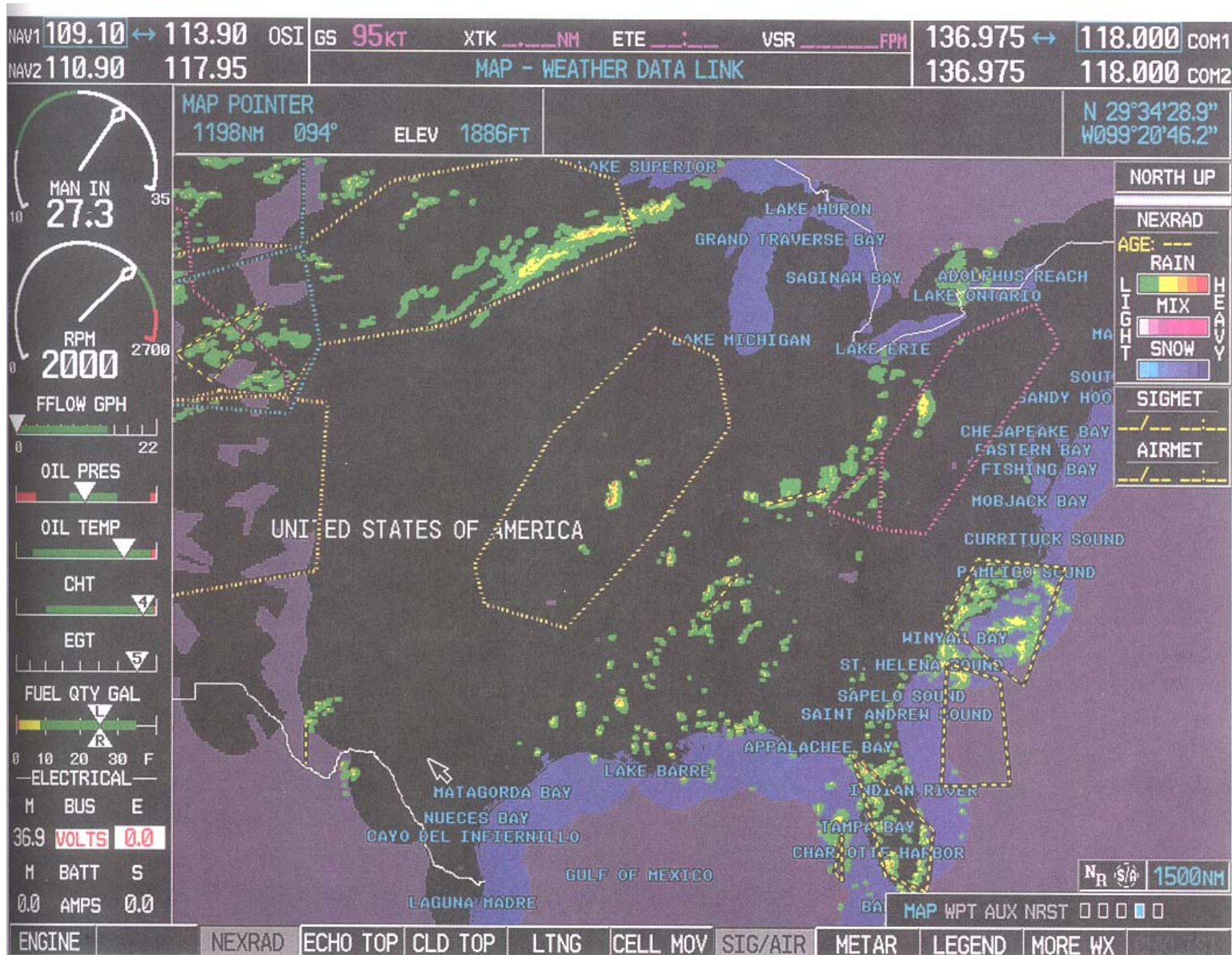


The MFD map can display terrain, traffic, nexrad, lightning



with the necessary optional equipment installed...

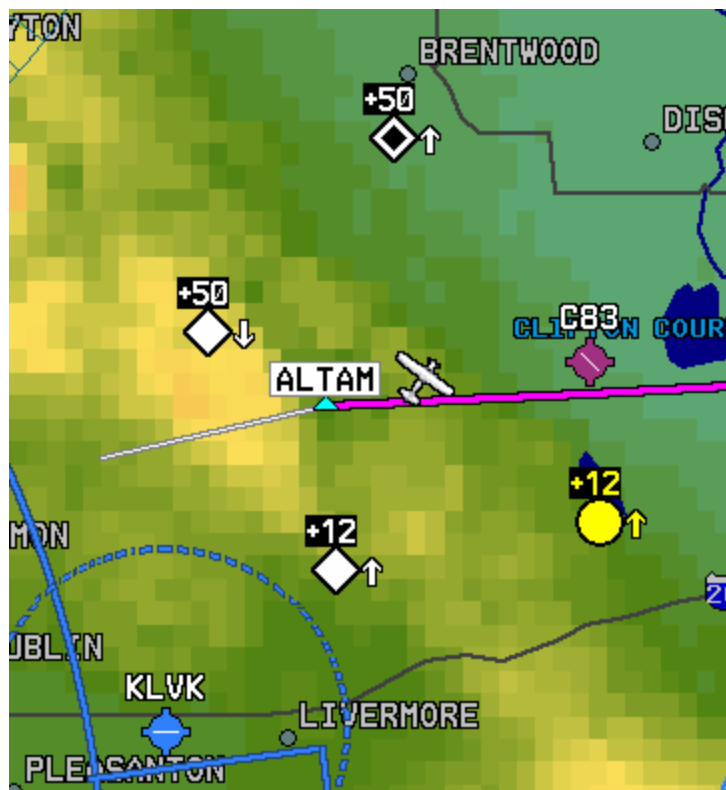
The MFD is showing XM NEXRAD data.



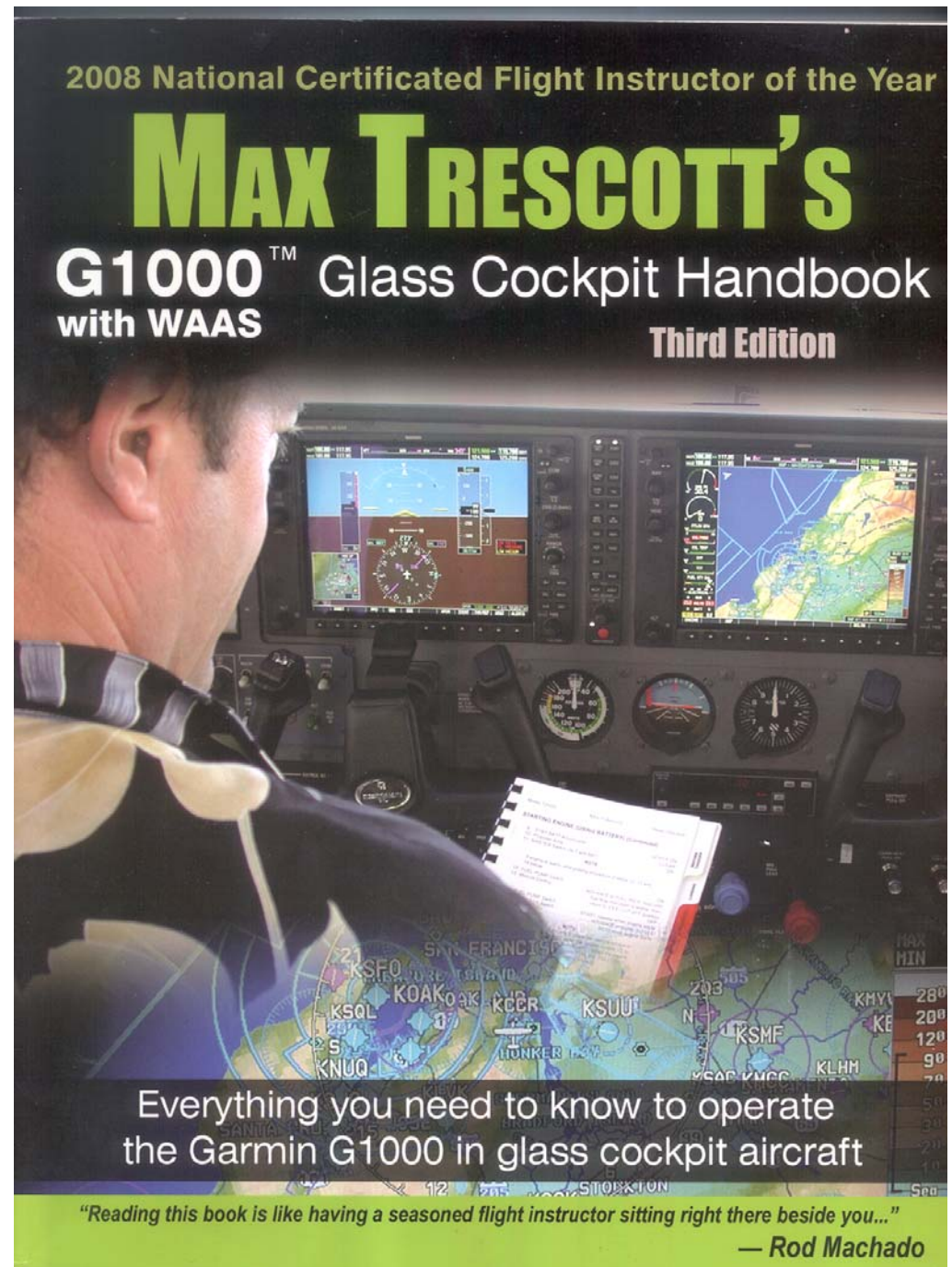
Traffic advisories are shown on the MFD and on the PFD map inset



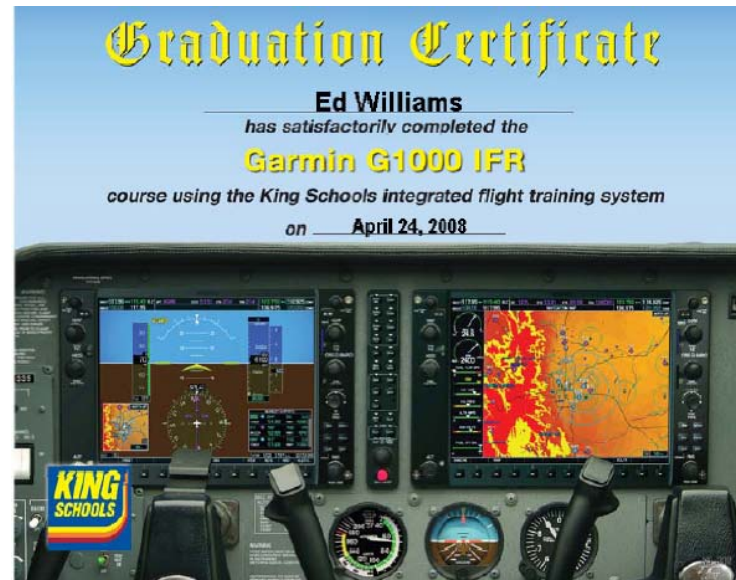
PFD map inset



I highly recommend this book...



The King School is a good overview -- but is \$249



The Garmin simulators are faithful and essential

Harder to “fly” than the 430/530 simulators IMO
Dual screens add realism.

FS –X supposedly has a partial simulation.

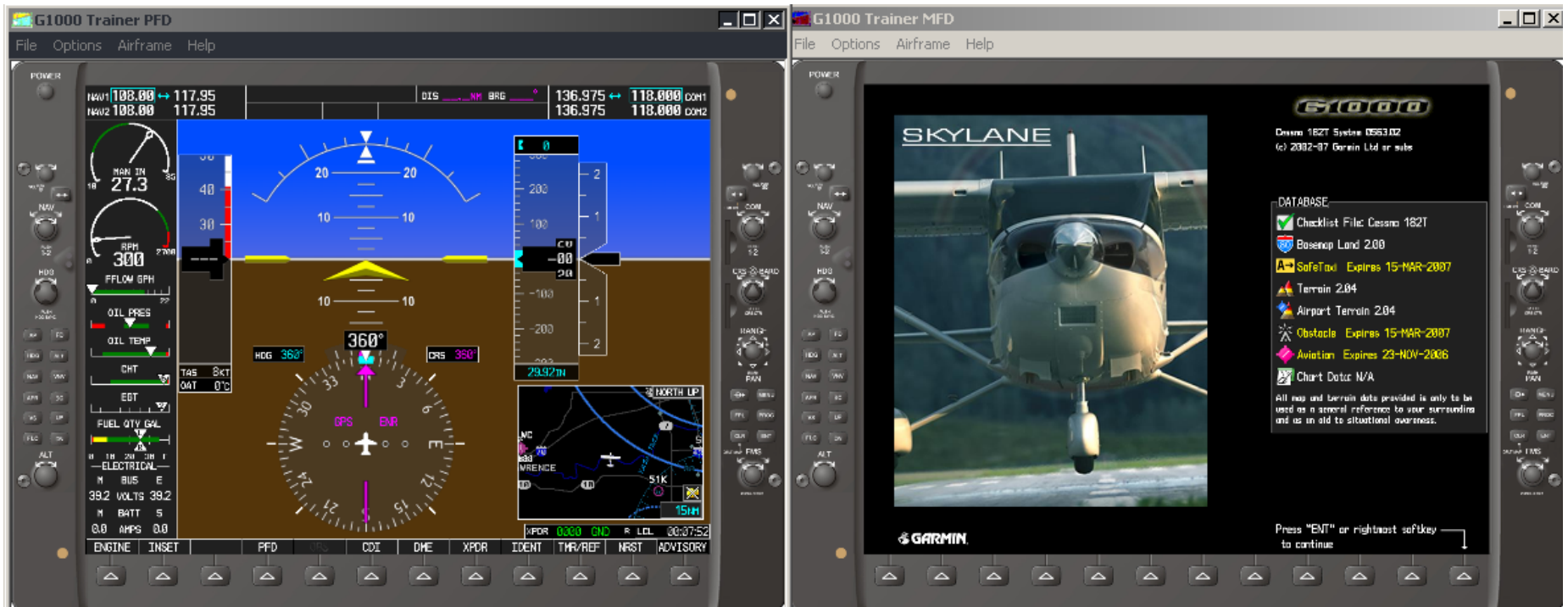


[G1000 PC Trainer for Cessna NAV III, version 8.20](#)

010-10596-04

\$ 24.95 USD

+ ADD TO CART



If you've not flown a glass panel, give it a try.

- I found the instrument display intuitive – easy to transition to.
- Practice with the simulator was greatly rewarded.
- The GPS is easy if you know the 430/530.
- Keep looking out the window!!